

# SNOPY: Bridging Sample Denoising with Causal Graph Learning for Effective Vulnerability Detection

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## ABSTRACT

Deep Learning (DL) has emerged as a promising means for vulnerability detection due to its ability to automatically derive features from vulnerable code. Unfortunately, current solutions struggle to focus on vulnerability-related parts of vulnerable functions, and tend to exploit spurious correlations for prediction, thus undermining their effectiveness in practice. In this paper, we propose SNOPY, a novel DL-based approach, which bridges sample denoising with causal graph learning to capture real vulnerability patterns from vulnerable samples with numerous noise for effective detection. Specifically, SNOPY adopts a change-based sample denoising approach to automatically weed out vulnerability-irrelevant code elements in the vulnerable functions without sacrificing the label accuracy. Then, SNOPY constructs a novel Causality-Aware Graph Attention Network (CA-GAT) with Feature Caching Scheme (FCS) to learn causal vulnerability features while maintaining efficiency. Experiments on the three public benchmark datasets show that SNOPY outperforms the state-of-the-art baselines by an average of 27.22%, 85.89%, and 75.50% in terms of F1-score, respectively.

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## CCS CONCEPTS

• Security and privacy → Software security engineering; • Computing methodologies → Artificial intelligence.

## KEYWORDS

Program Analysis, Causal Learning, Graph Attention Network

### ACM Reference Format:

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## 1 INTRODUCTION

Software vulnerabilities are security-related flaws introduced during the design and implementation of the software. Such weaknesses could be exploited by a threat actor for a variety of malicious ends [31]. For example, `XZ-Utils`<sup>1</sup>, a data-compression library widely integrated into Linux ecosystem, was recently disclosed to contain a backdoor (CVE-2024-3094<sup>2</sup>), enabling a remote attacker to execute arbitrary code. Thus, despite significant efforts to enhance software reliability in the past few decades, vulnerability detection remains a classic yet challenging problem.

Due to the high flexibility for analyzing software without running it, static code analyzers [2, 6, 9, 23] are widely used to hunt security vulnerabilities hidden in programs. However, state-of-the-art tools have achieved limited success in realistic scenarios as they heavily rely on hand-crafted vulnerability specifications and rules, which are *time-consuming* and *error-prone* [40]. Benefiting from the construction of large-scale vulnerability datasets [10, 20, 46] and tremendous progresses of Deep Learning (DL) in code understanding, recent years have witnessed an increasing in the popularity of

<sup>1</sup><https://tukaani.org/xz/>

<sup>2</sup><https://nvd.nist.gov/vuln/detail/CVE-2024-3094>

learning-based vulnerability detection approaches [11, 38, 39, 71]. Compared to conventional Program Analysis (PA)-based solutions, DL-based approaches can automatically learn implicit vulnerability patterns from source code without human intervention.

While promising, current neural vulnerability detectors suffer from severe performance degradation when applied to detect vulnerabilities in real-world settings, posing a barrier to adoption [8]. Such poor generalization ability stems from two major **challenges**:

**Challenge 1: Noisy program semantics.** Since acquiring a reliable vulnerability label is a non-trivial task, previous neural vulnerability detectors [3, 36, 59, 71] primarily extract features from the entire functions, instead of vulnerability-related code regions. As a result, DL models will be heavily influenced by the program semantics of vulnerability-irrelevant code elements (i.e., *noise*) in the vulnerable samples. To alleviate this problem, a straightforward countermeasure is program slicing [60], which prunes irrelevant statements starting from a Point of Interest (PoI), as recent works [4, 38, 39] do. Unfortunately, such pre-processing still requires specialized security expertise (e.g., slicing criteria), and is limited to specific types of vulnerabilities [63]. Moreover, since a considerable portion (e.g., accounting for 24.19% in the Big-Vul [20] dataset) of vulnerabilities are fixed by adding compulsory security checks without any deletion, existing deletion-based annotation rules (i.e., a slice is considered to be vulnerable as long as it covers at least one vulnerable statement removed in the security patch [11]) may not work and even introduce additional data quality issues [15].

**Challenge 2: Learning spurious correlations.** Recent works [37, 66] pointed out that, both traditional Deep Neural Network (DNN)-based and emerging Large Language Model (LLM)-based vulnerability detectors can be easily fooled into flipping their decisions by simple perturbations such as identifier replacement. This is because DL models tend to pick up dataset nuances (e.g., specific coding styles) for prediction [56], as opposed to causal vulnerability features (e.g., potential root causes and manifestation points) [43]. To cut off the correlations between spurious features and model outputs, state-of-the-art approaches either retrain detection models on obfuscated program variants [7] or ignore the spurious features during the inference phase [50]. For example, Rahman et al. [50] assumed variable and API names can be abused as spurious features, and prevented them from participating in decision-making. Nevertheless, current solutions focus on enhancing the robustness of detection models against target samples with spurious features, instead of capturing real vulnerability patterns, resulting in marginal performance improvements.

**Our Work.** Based on the above discussion, an important question arises as “*how to capture real vulnerability patterns from vulnerable samples with numerous noise for effective detection?*” In response, we propose **SNOPY**, a novel DL-based approach, which combines **S**ample **d**e**NO**ising with causal **g**ra**Ph** learning for effective vulnerability detection. The key insights underlying our approach include (1) patch modifications aim to sanitize or interrupt vulnerable program behaviors, and naturally can be utilized as *explicit expert knowledge* to localize vulnerability-related code regions, as well as (2) the relationships between causal vulnerability features and prediction labels should be invariant, regardless of changes in spurious parts. Specifically, to solve the first issue, inspired by that Vulnerability-Fixing Commits (VFCs) are the most common source

of current vulnerability datasets [16], **SNOPY** adopts a change-based sample denoising approach to automatically weed out vulnerability-irrelevant code elements in the vulnerable functions without sacrificing the label accuracy. To address the second issue, **SNOPY** constructs a Causality-Aware Graph Attention Network (CA-GAT) to approximately disentangle causal and spurious features from vulnerable samples based on attention mechanism [58], and maximize the causal effect of real vulnerability patterns on predicting labels while ignoring the spurious parts. In addition, given the diversity of spurious features in practice, CA-GAT incorporates a novel Feature Caching Scheme (FCS) to reuse previously identified spurious features without significantly raising memory consumption.

**Evaluation.** We implement a prototype system of **SNOPY**, and conduct comparative experiments with nine prior DL-based vulnerability detection approaches [8, 11, 24, 36, 38, 39, 45, 61, 71] on the three well-regarded VFC-based benchmark datasets, including FFmpeg+QEMU [71], Big-Vul [20], and DIVERSEVUL [10]. Experimental results show that **SNOPY** outperforms the state-of-the-art baselines with respect to F1-score. In particular, compared to the best-performing baseline SVuLD [45], **SNOPY** achieves 2.35%, 13.20%, and 6.72% relative improvements on the three datasets, respectively. In addition, when applied to detect different types of vulnerabilities, **SNOPY** produces substantial improvements of up to 21.80% in terms of F1-score on average than SVuLD.

**Contributions.** This paper makes the following contributions:

- We propose a novel DL-based approach, **SNOPY**<sup>3</sup>, which bridges real sample denoising with causal graph learning to capture real vulnerability patterns from vulnerable samples with numerous noise for effective detection.
- We propose a novel Causality-Aware Graph Attention Network (CA-GAT) with Feature Caching Scheme (FCS) to learn causal vulnerability features while maintaining efficiency.
- We evaluate **SNOPY** against nine existing DL-based vulnerability detection approaches on the three large-scale benchmark datasets. The extensive experiment results indicate that **SNOPY** outperforms the state-of-the-art baselines.

**Paper Organization.** The remainder of this paper is organized as follows. Section 2 introduces the background knowledge related to our problem, and discusses the limitations of existing solutions. Section 3 describes the details about our approach. Section 4 presents the experimental setup, followed by the evaluation results in Section 5. Section 6 discusses the possible threats to validity. Section 7 reviews the related work. Section 8 summarizes this paper and outlines our future research agenda.

## 2 BACKGROUND AND MOTIVATION

### 2.1 Background

**Vulnerability-Fixing Commits (VFCs)**, also known as *Security Patches* [34], are code changes that correct the vulnerabilities that already exist in repositories. They are commonly released to the public through official channels or vulnerability advisories, such as Common Vulnerabilities and Exposures (CVE) [13] and National Vulnerability Database (NVD) [44], for security management.

<sup>3</sup><https://github.com/SnopyArtifact/Snopy>

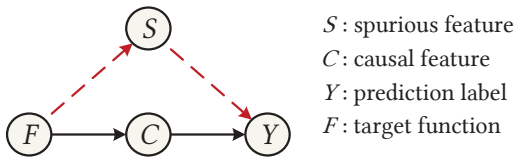


Figure 1: Structural causal model for DL-based vulnerability detection.

Vulnerability-Contributing Commits (VCCs) are code changes in which the vulnerable lines of code were firstly added [42]. A straightforward way to identify VCCs is SZZ algorithm [52], which assumes that the lines of code deleted by the VFCs are the same as or evolved from the lines of code added by the VCCs.

Structural Causal Model (SCM) [49] is a directed acyclic graph that describes causal relationships between different variables. If a variable  $B$  depends on  $A$  to determine its value, the variable  $A$  is a cause of  $B$  and the arrow  $A \rightarrow B$  indicates the causal relationship. Figure 1 presents the causalities among four variables in the context of DL-based vulnerability detection, in which the variable  $C$  denotes the causal feature that truly reflects the intrinsic property of a vulnerability while the variable  $S$  represents the spurious feature which is usually caused by the data biases (e.g., specific coding styles). Based on the feature representation of a target function  $F$ , the neural vulnerability detector extracts the discriminative part to produce a prediction label  $Y$  (1 for vulnerable and 0 otherwise).

Scrutinizing this causal graph, we can recognize a backdoor path  $F \rightarrow S \rightarrow Y$  between the target function  $F$  and its prediction label  $Y$ , wherein the spurious feature  $S$  plays a confounder role that establishes the statistical (but not causal) correlation which only exists in training but not in testing. As a result, the deployed detection model may suffer from serious performance degradation once the testing data distribution shifts from the original training data. To eliminate the backdoor path, a promising solution is **causal intervention** [49], which pairs each causal feature with various types of spurious features that appear in the dataset and promotes invariant relationships between causal features and predictions, regardless of changes in spurious parts.

## 2.2 Motivating Example

To illustrate the limitations of existing neural vulnerability detectors and motivate the key insight of our approach, we use a real-world vulnerability CVE-2018-9518<sup>4</sup> as a running example.

Figure 2 exemplifies the fixing commit of this vulnerability. Since the data type of `tlv_len` is `u8` (i.e., unsigned char), there exists out-of-bounds write when `uri_len` is allocated to it (line 15) without bounds checking. This issue could lead to local escalation of privilege, allowing an attacker to cause a denial of service (system crash) or possibly execute arbitrary code. To fix this vulnerability, developers perform compulsory security checks (lines 10-11) to limit the size of `uri_len` to avoid writing past the end of the allocated buffer. Benefiting from the superior capability to automatically extract features from source code, DL techniques have emerged as promising solutions for vulnerability detection [8, 24, 71]. However, as shown

```

Vulnerability-Fixing Commit (fe9c8426) of CVE-2018-9518
1 diff --git a/net/nfc/llcp_commands.c b/net/nfc/llcp_commands.c
2 index 367d8c0..2ceefaf1 100644
3 --- a/net/nfc/llcp_commands.c
4 +++ b/net/nfc/llcp_commands.c
5 @@ -149,6 +149,10 @@ struct nfc_llcp_sdp_tlv
6      *nfc_llcp_build_sdpreq_tlv(u8 tid, char *uri,
7                               size_t uri_len);
8 {
9     struct nfc_llcp_sdp_tlv *sdpreq;
10    pr_debug("uri: %s, len: %zu\n", uri, uri_len);
11    if (WARN_ON_ONCE(uri_len > U8_MAX - 4))
12        return NULL;
13    sdpreq = kzalloc(sizeof(struct nfc_llcp_sdp_tlv), GFP_KERNEL);
14    if (sdpreq == NULL)
15        return NULL;
16    sdpreq->tlv_len = uri_len + 3;
17    if (uri[uri_len - 1] == 0)
18        sdpreq->tlv_len--;
19    sdpreq->tlv = kzalloc(sdpreq->tlv_len + 1, GFP_KERNEL);
20    if (sdpreq->tlv == NULL) {
21        kfree(sdpreq);
22        return NULL;
23    }
24    sdpreq->tlv[0] = LLCP_TLV_SDREQ;
25    sdpreq->tlv[1] = sdpreq->tlv_len - 2;
26    sdpreq->tlv[2] = tid;
27    sdpreq->tid = tid;
28    sdpreq->uri = sdpreq->tlv + 3;
29    memcpy(sdpreq->uri, uri, uri_len);
30    sdpreq->time = jiffies;
31    INIT_HLIST_NODE(&sdpreq->node);
32    return sdpreq;
33 }
    
```

Point of Interest  
Affected Fragments  
-----> Data-flow

Figure 2: A motivating example from Linux Kernel.

in this case, the core logic of a vulnerability generally involves only a few statements, while the whole function contains dozens (mostly hundreds) of lines of code. As a result, these program semantics of vulnerability-irrelevant code elements (i.e., noise) will heavily influence the DL model.

To mitigate the noise problem, an intuitive way is to perform program slicing [60] from vulnerability-prone program points of interest (e.g., sensitive APIs, pointer usage) to prune irrelevant statements [4, 38, 39, 63]. For example, DEEPWUKONG [11] performed forward and backward control- and data-flow slicing based on *system API calls* and *arithmetic operators* to extract graph slices for feature extraction. As shown in Figure 2, starting from the yellow-shaded expression statement `sdpreq->tlv_len = uri_len + 3` (i.e., a vulnerability-triggering statement at line 15), we can obtain a set of vulnerability-related contexts (purple-shaded) with data-dependencies (red arrow) by traversing the Program Dependence Graph (PDG) [22]. Despite their effectiveness, such pre-processing relies heavily on the expertise of the developers performing the analysis, and the knowledge (e.g., sources and sinks) of existing vulnerabilities. What’s worse, according to their annotation rules (i.e., statements removed from the patched function are vulnerability-related), the code slice (yellow- and purple-shaded statements) in our motivating example will be mislabeled as *benign* because it does not contain any deletion. According to our statistical analysis on the widely-used vulnerability dataset Big-Vul [20], 24.19% vulnerable samples are fixed only with additions. This observation reveals the challenge slicing-based solutions may face in practice.

Another common approach is model-centric, which guides the DL model to autonomously learn the critical aspects (i.e., code elements of high importance) of the input sample without human

<sup>4</sup><https://nvd.nist.gov/vuln/detail/CVE-2018-9518>



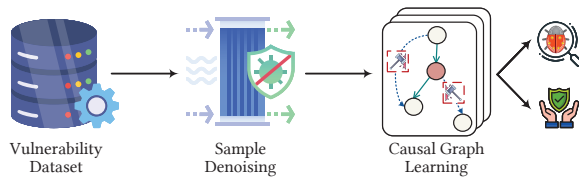


Figure 3: Workflow of SNOPI.

intervention. For instance, by employing the edge-aware attention module as well as a kernel-scaled convolutional layer, AMPLE [61] estimated the importance of each edge and node and correctly identified this motivating example as vulnerable. However, recent works [7, 50] have revealed that both state-of-the-art DNN- and LLM-based approaches tend to rely on non-causal features as shortcuts to make predictions. Thus, we further calculate the node importance to locate the Top-5 important statements (an acceptable threshold on manual inspection [24, 36]) likely to be vulnerable. Unfortunately, neither the vulnerability-triggering statement (line 15) nor its corresponding contexts (purple-shaded fragments in Figure 2) are captured by AMPLE for prediction. To alleviate the problem, CausalVul [50] assumed variable and API names can be abused as spurious features, and prevented models from using them for prediction. However, crafting hundreds of variants to test various spurious features that can occur in code is not practical, and the contextual semantics of variable names (e.g., `uri_len`) are beneficial to identifying the potential buffer overflow in this case.

**Our Idea.** In summary, current neural vulnerability detectors (❶) struggle to focus on vulnerability-related parts code elements, and (❷) tend to exploit spurious correlations for prediction, thus undermining their effectiveness in practice. Naturally, we ask the question, “*how to capture real vulnerability patterns from vulnerable samples with numerous noise for effective detection?*” For this example, the statements added by the VFC pinpoint the vulnerability-related variable `uri_len` (line 10). Such *explicit expert knowledge* can serve as the slicing criterion that enables us to weed out vulnerability-irrelevant parts of vulnerable functions while ensuring the label accuracy. As for the spurious correlation issue, we can leverage the attention mechanism [58] to approximately disentangle causal and spurious features on representation-level, and maximize the causal effect of real vulnerability patterns on predicting labels while ignoring the spurious parts.

### 3 METHODOLOGY

#### 3.1 Overview of SNOPI

Figure 3 illustrates the overall workflow of SNOPI. The key technical contributions of SNOPI include: (❶) sample denoising, which weeds out the vulnerability-irrelevant parts of vulnerable functions for representation, and (❷) causal graph learning, which captures real vulnerability patterns for prediction. In the deployment phase, SNOPI works like a typical neural vulnerability detector [8, 36, 71] to discover vulnerabilities at the function-level. We present the details of SNOPI in the following subsections.

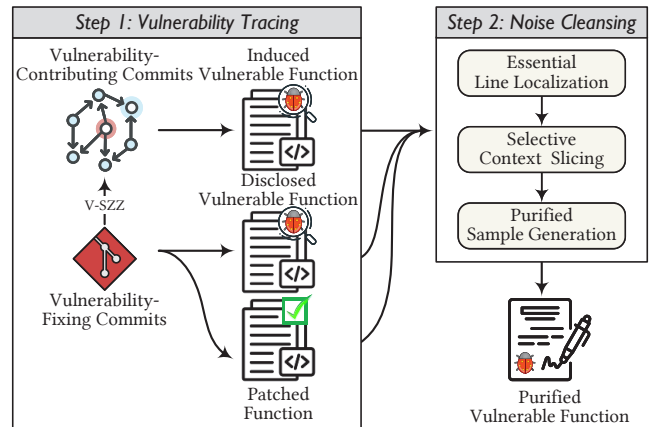


Figure 4: Overview of sample denoising.

#### 3.2 Sample Denoising

As mentioned before, feeding the entire vulnerable function into the DL model will inevitably introduce a large amount of vulnerability-irrelevant code elements that form noise, while extracting finer-grained program slices may suffer from imprecise labeling strategy and expensive expertise. Motivated by the fact that current vulnerability datasets [10, 20, 46] primarily collect vulnerable samples from Vulnerability-Fixing Commits (VFCs), we propose a change-based sample denoising strategy, which conducts noise cleansing based on the modifications between vulnerable functions and corresponding patched versions to automatically weed out the noise information in the vulnerable functions, as shown in Figure 4.

**3.2.1 Vulnerability Tracing.** We first execute the `git reset` command to exactly roll back the source code to the point before and after applying the patch based on the commit ID provided by the vulnerability dataset. Then, we localize all functions involving code revisions and their scopes according to the line numbers of changed code in the VFC’s header lines starting with `---` and `+++` (e.g., lines 3–4 in Figure 2), and obtain the vulnerable and corresponding patched functions in pre- and post-commit versions via the `ctags`<sup>5</sup> parser. In addition, considering that a VFC may also contain vulnerability-irrelevant non-essential changes [32] (e.g., variable renaming, cascaded adaptations), we further leverage the state-of-the-art V-SZZ algorithm [1] to collect Vulnerability-Contributing Commits (VCCs) as references to (❶) confirm truly vulnerable statements, and (❷) narrow the search space for vulnerability-related contexts in the later noise cleansing phase. Our intuition is that vulnerability semantics persist and propagate across multiple versions (from the vulnerability introduction to the vulnerability patch) of the vulnerable functions, regardless of other internal modifications which are often benign [42]. For clarity, we refer to the vulnerable function that is identified from the VFC as the **disclosed vulnerable function**, and the vulnerable function that is identified from the VCC as the **induced vulnerable function**.

Specifically, V-SZZ first performs code similarity checking based on the edit distance to map the deleted line (annotated by the VFC)

<sup>5</sup><https://ctags.io/>

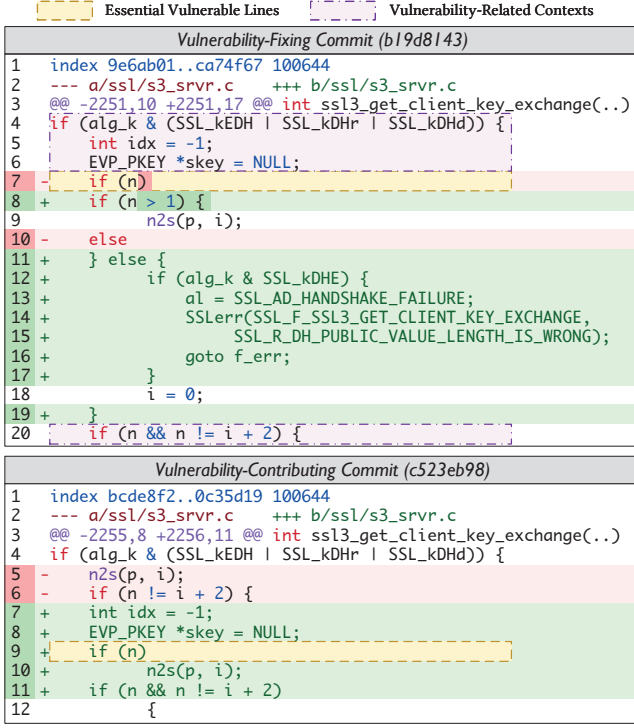


Figure 5: A working example from OpenSSL.

in the disclosed vulnerable function to the line in the previous version. Then, it executes the `git blame` command to trace all previous commits that touched the code changes in VFCs, and considers the earliest one as the VCC. Based on these retrieved VCCs, we repeat the previously procedure to extract the induced versions of disclosed vulnerable functions. The only difference lies in that the induced vulnerable function is extracted from the post-commit version, rather than the pre-commit version.

**3.2.2 Noise Cleansing.** Given a 3-tuple of a vulnerability, i.e., the induced vulnerable function  $f_i$ , the disclosed vulnerable function  $f_d$ , and the patched function  $f_p$ , SNOPY conducts noise cleansing to extract the vulnerability-related part. Generally, an ideal vulnerable sample should only cover (1) essential vulnerable lines revealing how a vulnerability is caused, and (2) contextual statements reflecting the environment where the vulnerability manifests.

**Essential Line Localization.** Following prior works [62, 64], essential vulnerable lines  $E_{vul}$  are statements  $st$  removed from  $f_p$  but included in  $f_i$  and  $f_d$ , and are formally defined as:

$$E_{vul} = \{st | (st \in (f_d \setminus f_p)) \wedge (st \in (f_i \cap f_d))\} \quad (1)$$

Considering that  $f_i$  and  $E_{vul}$  are not available when a vulnerability is fixed purely with additions (e.g., the motivating example in Figure 2), we further identify essential patch lines  $E_{patch}$  that are added in  $f_p$  but do not exist in  $f_d$ :

$$E_{patch} = \{st | (st \in (f_p \setminus f_d))\} \quad (2)$$

**Selective Context Slicing.** To precisely extract contextual statements  $E_{con}$  which have a major impact on vulnerability manifestation, we perform selective program slicing on  $f_d$ , which can be in two directions: backward and forward slicing.

- **Backward slicing** aims to localize the statements that have dependencies with essential vulnerable lines  $E_{vul}$  (or essential patch lines  $E_{patch}$  if  $E_{vul}$  is not available). Like normal backward slicing, we preserve all statements that have influence on  $E_{vul}$  ( $E_{patch}$ ) with respect to data- and control- dependencies.
- **Forward slicing** is to find statements affected by the vulnerability. Since taking all the subsequent statements into account will cover too many irrelevant statements [39, 64], we perform (1) forward data-flow slicing as target statements receive variables/parameters assigned or checked by  $E_{vul}$  ( $E_{patch}$ ), and (2) forward control-flow slicing only if the result of previous data-flow slicing is empty.

As a working example, let us consider CVE-2015-1787<sup>6</sup>, an improper input validation vulnerability discovered in OpenSSL. Figure 5 shows its VFC (top) and VCC (bottom). Among the red-shaded statements deleted from  $f_d$ , only the yellow-shaded statement `if (n)` (i.e., line 7 in  $f_d$  and line 9 in  $f_i$ ) belongs to  $E_{vul}$ . By performing the selective contextual statement slicing from  $E_{vul}$ , statements that have backward control- and data-dependencies (i.e., lines 4-6 in  $f_d$ ) and forward data-dependencies (i.e., line 20 in  $f_d$ ) are included in  $E_{con}$ .

**Purified Sample Generation.** After backward and forward program slicing, all essential vulnerable lines  $E_{vul}$  (if any) and the corresponding sliced contextual statements  $E_{con}$  are retained to generate the purified version of the disclosed vulnerable function  $f_d$ . These purified vulnerable functions will be fed along with benign samples into the DL model for training. It is noteworthy that sample denoising is only applied in the training phase because the VFC for a vulnerability is not available before it is detected.

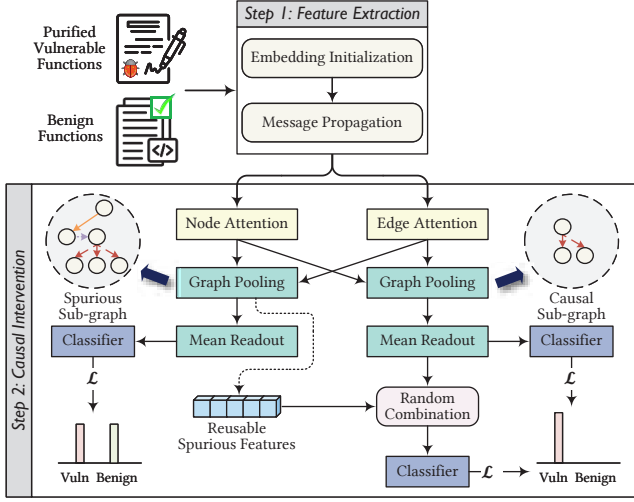
### 3.3 Causal Graph Learning

To encourage the detection model to leverage real vulnerability patterns for prediction, we propose a novel Causality-Aware Graph Attention Network (CA-GAT), with detailed architecture presented in Figure 6. The CA-GAT consists of two main components: (1) the feature extraction module for learning precise code representations; and (2) the causal intervention module which promotes invariant relationships between causal feature and model outputs, regardless of changes in spurious parts.

**3.3.1 Feature Extraction.** The feature extraction process is divided into two parts: embedding initialization and message propagation. **Embedding Initialization.** Following [8, 61, 71], we reason about vulnerability patterns based on Code Property Graph (CPG) [65], a popular data structure which offers rich syntactic and semantic information of source code. Formally, a CPG is denoted as  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ , where  $\mathcal{V}$  and  $\mathcal{E}$  represent the set of nodes and edges, respectively. Each node  $v \in \mathcal{V}$  is initialized as a  $m$ -dimensional feature vector  $h_v^{(0)} \in \mathbb{R}^m$  by the pre-trained CodeBERT [21] model.

**Message Propagation.** To explicitly incorporate graph-structured contextual semantics into the representations of CPG nodes, we

<sup>6</sup><https://nvd.nist.gov/vuln/detail/CVE-2015-1787>



**Figure 6: Illustration of our proposed Causality-Aware Graph Attention Network (CA-GAT).**

employ a tailored message propagation mechanism [41] to update node features throughout graphs. To be specific, the embedding  $\mathbf{h}_v^{(t)}$  of node  $v$  at time step  $t \leq T$  is updated by:

$$\mathbf{h}_v^{(t)} = \text{LeakyReLU}\left(\mathbf{W}^{(t)}(\mathbf{h}_v^{(t-1)} \parallel \mathbf{h}_{\mathcal{N}(v)}^{(t-1)})\right) \quad (3)$$

where  $\mathbf{W}^{(t)}$  is a learnable transformation matrix at  $t$ -th iteration.  $\parallel$  denotes the concatenation operator.  $\mathcal{N}(v)$  represents the 1-hop neighbors of node  $v$ .  $\mathbf{h}_{\mathcal{N}(v)}^{(t-1)}$  is the neural information propagated from  $\mathcal{N}(v)$  to node  $v$  at previous time step:

$$\mathbf{h}_{\mathcal{N}(v)}^{(t-1)} = \sum_{u \in \mathcal{N}(v)} \gamma_{u,v} \mathbf{h}_j^{(t-1)} \quad (4)$$

where  $\gamma_{u,v}$  is a decay factor that specifies how much information is passed from node  $u$  to node  $v$  along with the edge  $u \rightarrow v$ , and is formally designed as:

$$\gamma_{u,v} = \frac{1}{\sqrt{|\mathcal{N}(u)| |\mathcal{N}(v)|}} \quad (5)$$

where  $|\mathcal{N}(u)|$  and  $|\mathcal{N}(v)|$  denote the number of 1-hop neighbors for node  $u$  and node  $v$ , respectively.

The above message propagation procedure iterates over  $T$  time steps, and the final node representation matrix is  $\mathbf{X} \in \mathbb{R}^{|\mathcal{V}| \times m}$ , in which  $\mathbf{h}_v^{(T)} = \mathbf{X}[v, :]$ .

**3.3.2 Causal Intervention.** To promote the detection model learning real vulnerability patterns, we propose a novel causal intervention module with Feature Caching Scheme (FCS).

Specifically, Given an encoded CPG  $\mathcal{G}$  with the adjacency matrix  $\mathbf{A} \in \{0, 1\}^{|\mathcal{V}| \times |\mathcal{V}|}$  and node representation matrix  $\mathbf{X}$ , we first employ two Multi-Layer Perceptrons (MLP) [57] to calculate node-level and edge-level attention scores as follows:

$$\alpha_{c_v}, \alpha_{s_v} = \text{softmax}\left(\text{MLP}_{\text{node}}(\mathbf{h}_v)\right) \quad (6)$$

$$\beta_{c_{vu}}, \beta_{s_{vu}} = \text{softmax}\left(\text{MLP}_{\text{edge}}(\mathbf{h}_v \parallel \mathbf{h}_u)\right) \quad (7)$$

where  $\alpha_{c_v}$  ( $\beta_{c_{vu}}$ ) represents the node (/edge)-level attention score for node  $v$  (/edge  $v \rightarrow u$ ) in the sub-graph containing causal features (hereafter, causal sub-graph  $\mathcal{G}_c$ ) of graph  $\mathcal{G}$ . Similarly,  $\alpha_{s_v}$  and  $\beta_{s_{vu}}$  are for spurious sub-graph  $\mathcal{G}_s$ . Note that  $\alpha_{c_v} + \alpha_{s_v} = 1$ , and  $\beta_{c_{vu}} + \beta_{s_{vu}} = 1$ .

Based on the node-level and edge-level attention scores, we can decompose the original CPG  $\mathcal{G}$  into the initial causal sub-graph  $\mathcal{G}_c$  and spurious sub-graph  $\mathcal{G}_s$ , and produce graph-level representations for them:

$$\mathbf{h}_{\mathcal{G}_c} = \varphi\left(\text{GPL}(\mathbf{A} \odot \mathbf{M}_c, \mathbf{X} \odot \mathbf{F}_c)\right) \quad (8)$$

$$\mathbf{h}_{\mathcal{G}_s} = \varphi\left(\text{GPL}(\mathbf{A} \odot \mathbf{M}_s, \mathbf{X} \odot \mathbf{F}_s)\right) \quad (9)$$

where  $\varphi(\cdot)$  and  $\text{GPL}(\cdot)$  represent the graph mean readout layer and pooling layer, respectively.  $\odot$  denotes element-wise multiplication.  $\mathbf{M}_c \in \{0, 1\}^{|\mathcal{V}| \times |\mathcal{V}|}$  and  $\mathbf{F}_c \in \{0, 1\}^{|\mathcal{V}| \times m}$  represent the edge mask and feature mask for the causal sub-graph  $\mathcal{G}_c$ . Analogously,  $\mathbf{M}_s$  and  $\mathbf{F}_s$  are for the spurious sub-graph  $\mathcal{G}_s$ .

Having obtained the representations of the causal sub-graph  $\mathcal{G}_c$  and spurious sub-graph  $\mathcal{G}_s$ , we would like the detection model being able to disentangle them during training process for better predictions. To do so, we employ the standard cross-entropy loss over the training samples  $\mathcal{D}$  to ensure the correctness of predictions based on causal features:

$$\mathcal{L}_{CE} = -\frac{1}{|\mathcal{D}|} \sum_{\mathcal{G} \in \mathcal{D}} \mathbf{y}_{\mathcal{G}}^{\top} \log(\Phi(\mathbf{h}_{\mathcal{G}_c})) \quad (10)$$

where  $\Phi(\cdot)$  is the MLP-based classifier with softmax function.

For spurious features, we push their predictions evenly to binary labels (i.e., vulnerable or benign) since they are unnecessary for classification [55]:

$$\mathcal{L}_{unif} = \frac{1}{|\mathcal{D}|} \sum_{\mathcal{G} \in \mathcal{D}} \text{KL}\left(\mathbf{y}_{unif}, \Phi(\mathbf{h}_{\mathcal{G}_s})\right) \quad (11)$$

where  $\text{KL}$  denotes the KL-Divergence.  $\mathbf{y}_{unif}$  represents the uniform prior distribution.

As discussed in Section 2, causal intervention requires pairing the target causal feature per sample with various types of spurious features that appear in the dataset. For example, Ganz et al. [25] conditioned the causal sub-graph per sample with all possible spurious sub-graphs obtained during training. However, blindly traversing all possible spurious features (e.g., increasing the batch size) is unrealistic because any attribute of the input dataset that exhibits statistical correlation with the target label can be abused. To address this challenge, we propose a novel Feature Caching Scheme (FCS) to reuse previously identified spurious features. In each training epoch, we feed more data into the batch size (i.e.,  $N$  times the batch size) and store spurious features  $\mathbf{h}_{\mathcal{G}_s}$  into the cache space  $\mathcal{B} = \{\mathbf{h}_{\mathcal{G}_s} \rightarrow \mathbf{b}_i\}$ . In the intervention stage, we combine causal features with various spurious features in  $\mathcal{B}$ , and maximize the causal effect of real vulnerability patterns on predicting labels, regardless of changes in spurious parts:

$$\mathcal{L}_{cau} = -\frac{1}{|\mathcal{D}| \cdot |\mathcal{S}|} \sum_{\mathcal{G} \in \mathcal{D}} \sum_{s' \in \mathcal{S}} \mathbf{y}_{\mathcal{G}}^{\top} \log\left(\Phi(\mathbf{h}_{\mathcal{G}_c} \oplus \mathbf{h}_{\mathcal{G}_s'})\right) \quad (12)$$

where  $\mathcal{S}$  is the set of reusable spurious features appearing in the training data  $\mathcal{D}$ .  $\oplus$  denotes the random combination operation.



**Table 1: Statistics of the studied datasets**

Dataset	Vul	Non-vul	Ratio	VFCs	VCCs
FFmpeg+QEMU	12,460	14,858	1:1.2	6,611	6,439
Big-Vul	10,900	177,736	1:16.3	3,754	3,385
DIVERSEVUL	18,945	311,547	1:16.4	7,514	7,022

Finally, the total training loss is defined as:

$$\mathcal{L}_{total} = \mathcal{L}_{CE} + \lambda_1 \mathcal{L}_{unif} + \lambda_2 \mathcal{L}_{cau} \quad (13)$$

where  $\lambda_1$  and  $\lambda_2$  are two weight coefficients indicating the strength of feature disentanglement and causal intervention, respectively.

## 4 EXPERIMENTS

### 4.1 Research Questions

Our work seeks to answer three Research Questions (RQs):

- **RQ1: How does SNOPY perform compared to the state-of-the-art baselines on vulnerability detection?** By investigating this RQ, we aim to answer whether and to what extent can SNOPY outperform the state-of-the-art baselines in practice.
- **RQ2: How effective is SNOPY for detecting different types of vulnerabilities?** Current approaches primarily build a general-purpose model that can detect all vulnerabilities. Considering the characteristics and severity of different vulnerability types vary, we are interested to evaluate the detection performance of SNOPY across different types of vulnerabilities.
- **RQ3: How do various components of SNOPY affect its overall performance?** We perform two set of ablation studies to understand how different design choices, including the sample denoising (Section 3.2) and the causal graph learning (Section 3.3), impact the effectiveness of SNOPY.

### 4.2 Datasets

We chose benchmark datasets that satisfied the following criteria. First, they should be widely adopted by state-of-the-art baselines so that we can establish a fair comparison with them. Second, they are built upon VFCs since SNOPY is designed to utilize VFCs and VCCs to purify vulnerable code samples. Third, they include real-world vulnerabilities disclosed in diverse projects so that the generalization performance of approaches can be evaluated.

Based on the above criteria, we selected three popular datasets, including FFmpeg+QEMU [71], Big-Vul [20], and DIVERSEVUL [10].

- **FFmpeg+QEMU** [71] collected security-related commits via keywords matching, and manually labeled the pre-commit function in a VFC (/non-VFC) as vulnerable (/benign).
- **Big-Vul** [20] gathered vulnerabilities from VFCs linked to CVE. Unlike FFmpeg+QEMU, Big-Vul labeled the pre-commit version of a changed function to be vulnerable, and the post-commit version to be benign.
- **DIVERSEVUL** [10] crawled security issues to identify VFCs and extracted changed files based on relevant git commit URLs. It followed the same labeling strategy as the Big-Vul dataset.

The data statistics are shown in Table 1. Column 2 and Column 3 are the number of vulnerable and non-vulnerable functions, respectively. Column 4 denotes the ratio of vulnerable functions in each dataset. Column 5 presents the number of VFCs contained in each dataset. Column 6 reports the number of VCCs we collected from these VFCs by employing the V-SZZ algorithm. It is noteworthy that we exclude VCCs across functions (i.e., the induced vulnerable function that has an inconsistent function name as its disclosed/patched version) since SNOPY performs sample denoising based on code changes in VFCs and their corresponding VCCs.

### 4.3 Baselines

To evaluate our approach, we compared SNOPY with nine state-of-the-art baselines, including seven DNN-based approaches [8, 11, 36, 38, 39, 61, 71] and two LLM-based approaches [24, 45].

- **DNN-based Approaches.** VulDeePecker [39] and SySeVR [38] utilized BiLSTM to extract vulnerability semantics from program slices. Devign [71], REVEAL [8], IVDetect [36], DEEPWUKONG [11], and AMPLE [61] employed various graph neural networks to learn structural vulnerability features from code graphs.
- **LLM-based Approaches.** LINEVUL [24] employed a BERT architecture with self-attention layers to learn vulnerability semantics. SVulD [45] combined the strengths of pre-trained semantic embedding and contrastive learning to capture semantic representations of functions.

### 4.4 Experimental Setting

**Implementation details.** We implement SNOPY in Python using PyTorch [48]. Our experiments are performed on a Linux workstation with an Intel(R) Core(TM) i9-12900k @3.90GHz, 128GB RAM, and an NVIDIA GeForce RTX 3090 GPU with 24GB memory, running Ubuntu 18.04.4 LTS with CUDA 10.1. We employ a robust parser Joern [65] for CPG generation. Our CA-GAT model is trained in a batch-wise fashion until convergence and the batch size is set to 128. The number of propagation iterations  $T$  is set to 4. To mitigate the overfitting problem, we employ dropout [53] with a dropping ratio of 0.1. ADAM [33] optimizer is used to train the model with a learning rate of  $1e-2$ . The hyper-parameters are tuned through grid search. In light of the best performance, we report experimental results in a setting with the loss coefficients  $\lambda_1$  and  $\lambda_2$  as 0.6 and 0.5, and the capacity  $N$  of FCS as 6 on the three datasets.

**Evaluation metrics.** Following prior studies [8, 39, 71], we employ four widely-used binary classification metrics, including *Accuracy*, *Precision*, *Recall*, and *F1-score*, for evaluation. Accuracy evaluates the overall performance of classifiers. Precision refers to the ratio of truly vulnerable samples among the detected ones, while Recall measures the percentage of vulnerabilities that are retrieved out of all vulnerable instances. F1-score is the harmonic mean of Recall and Precision, and calculated as:  $2 \times \frac{Recall \times Precision}{Recall + Precision}$ .

## 5 EXPERIMENTAL RESULTS

### 5.1 RQ1: Detection Performance

**Experiment Setup.** We evaluate the nine aforementioned baselines (described in Section 4.3) and our proposed SNOPY on the three studied benchmark datasets (described in Section 4.2). We randomly

**Table 2: Comparison results between SNOPI and state-of-the-art baselines on the three datasets**

Metrics (%) \ Dataset	FFmpeg+QEMU [8]				Big-Vul [20]				DIVERSEVUL [10]			
	Accuracy	Precision	Recall	F1	Accuracy	Precision	Recall	F1	Accuracy	Precision	Recall	F1
VulDeePecker	48.55	33.96	27.47	30.37	83.27	16.56	22.95	19.24	87.44	11.30	24.55	15.48
SySeVR	44.63	35.70	61.87	45.28	82.45	19.63	28.91	23.38	86.16	7.69	14.28	10.00
Devign	51.37	48.15	80.42	60.24	85.64	27.32	13.04	17.65	87.16	24.49	28.07	26.16
REVEAL	53.05	54.19	75.32	63.03	83.79	15.34	30.05	20.31	85.32	20.69	33.19	25.49
IVDETECT	56.85	51.33	68.82	58.80	86.97	24.96	32.57	28.26	88.52	17.34	35.26	23.25
DEEPWUKONG	54.61	52.70	71.96	60.84	79.64	13.08	32.55	18.66	82.39	21.64	29.30	24.89
AMPLE	62.88	55.06	77.34	64.33	85.95	28.40	36.11	31.79	88.79	26.35	34.01	29.69
LINEVUL	63.74	52.44	65.39	58.21	80.26	12.96	38.32	19.37	90.52	<b>36.18</b>	26.98	30.91
SVuLD	60.51	54.99	<b>83.48</b>	66.30	<b>92.81</b>	33.24	41.65	36.97	<b>91.16</b>	31.44	40.17	35.27
SNOPI	<b>67.33</b>	<b>59.64</b>	78.72	<b>67.86</b>	90.75	<b>38.12</b>	<b>46.39</b>	<b>41.85</b>	89.61	33.76	<b>42.53</b>	<b>37.64</b>

split the benchmark dataset into 80%, 10%, and 10% for training, validation, and testing. For each subset, we keep the distribution as same as the original ones to align with the real-world setting.

**Results.** Table 2 presents the performance comparisons between SNOPI and state-of-the-art baselines on the three datasets regarding the four metrics (12 combination cases altogether), with the best results highlighted in bold. Overall, SNOPI achieves the best performance in the majority (8 out of 12) of cases. In particular, SNOPI outperforms all of the nine referred DNN-based and LLM-based approaches on the FFmpeg+QEMU, Big-Vul, and DIVERSEVUL dataset by an average of 27.22%, 85.89%, and 75.50% in terms of F1-score, respectively. Moreover, we observe that SVuLD performs better than all other baselines, although it neither focuses on vulnerability-prone code snippets like slice-level approaches [38, 39], nor explicitly utilizes the structural information of code like graph-based models [8, 11, 71]. This indicates the potential of LLM-based solutions in vulnerability detection as the size of the training set continues to expand. In contrast, our proposed SNOPI consistently achieves the best performance on the three datasets in terms of F1-score, outperforming SVuLD by 2.35%, 13.20%, and 6.72%, respectively. Such improvements demonstrate that SNOPI strikes a better balance between reporting more vulnerabilities and reducing false positive rates.

**Answer to RQ1:** The performance improvements of SNOPI over the state-of-the-art approaches are positive. Particularly, SNOPI outperforms the best-performing baseline SVuLD by 2.35%, 13.20%, and 6.72% in F1-score on the three datasets, respectively.

## 5.2 RQ2: Classification Performance

**Experiment Setup.** Common Weakness Enumeration (CWE) [14] provides a list of common software and hardware weakness types developed and maintained by security community. In particular, we focus on the Top-25 most dangerous CWEs because they are often easy to find and exploit, and should be prioritized for remediation. Here, we evaluate our SNOPI and the best-performing baseline SVuLD on two vulnerability datasets with CWE information, Big-Vul and DIVERSEVUL. Minor types of vulnerabilities (i.e., sample size less than 100) are excluded to avoid the under-fitting issue due to insufficient training samples. Finally, 8 types of vulnerabilities in the Big-Vul dataset and 12 types of vulnerabilities in the DIVERSEVUL

**Table 3: The F1-score of our SNOPI and baselines for the Top-25 most dangerous CWEs in Big-Vul and DIVERSEVUL**

Dataset	Rank	Type	Ratio	SVuLD	SNOPI
Big-Vul	1	CWE-787	2.25%	69.44	<b>73.89</b>
	4	CWE-416	3.76%	54.71	<b>68.32</b>
	6	CWE-20	13.62%	<b>62.99</b>	61.43
	7	CWE-125	7.12%	56.38	<b>69.47</b>
	12	CWE-476	2.45%	37.59	<b>75.23</b>
	14	CWE-190	3.50%	68.53	<b>72.06</b>
	17	CWE-119	24.22%	45.77	<b>69.28</b>
	21	CWE-362	3.17%	60.28	<b>65.33</b>
	<b>Average</b>				56.96
DIVERSEVUL	1	CWE-787	17.98%	<b>60.47</b>	56.99
	4	CWE-416	6.24%	53.58	<b>66.29</b>
	6	CWE-20	8.16%	44.39	55.83
	7	CWE-125	11.60%	49.51	62.30
	8	CWE-22	1.25%	<b>33.65</b>	26.74
	12	CWE-476	6.05%	22.01	<b>58.14</b>
	13	CWE-287	0.67%	8.24	13.59
	14	CWE-190	4.86%	<b>61.77</b>	48.25
	17	CWE-119	10.14%	56.74	<b>64.82</b>
	21	CWE-362	2.84%	38.13	<b>55.94</b>
	22	CWE-269	1.22%	6.99	13.34
	23	CWE-94	0.87%	11.37	17.55
	<b>Average</b>				37.24

dataset are covered in our experiment. The first four columns of Table 3 summarize their descriptive statistics. In terms of quantity, CWE-119 (Improper Restriction of Operations within the Bounds of a Memory Buffer) and CWE-787 (Out-of-bounds Write) have the largest proportion in the Big-Vul and DIVERSEVUL dataset, with 24.22% and 17.98%, respectively. We build a unified model and shuffle the dataset based on vulnerability types in parallel to ensure that different types of vulnerabilities are evenly distributed in each subset. For example, 80% vulnerable samples belonging to CWE-119 are demarcated as training set, and the remaining 20% samples are divided into two halves for validation (10%) and testing (10%). We compute the F1-score to evaluate the ability of each approach to correctly predict specific types of vulnerabilities.

**Results.** The experimental results are presented in Table 3. Despite suboptimal performance in detecting certain types of vulnerabilities, our proposed SNOPI outperforms the previous best-performing



baseline SVuLD in the majority of cases, with an average improvement of 21.80% and 20.78% in terms of F1-score on the Big-Vul and DIVERSEVUL dataset, respectively. Particularly, SNOPY obtains the highest F1-score of 75.23% on CWE-476 (NULL Pointer Dereference) in the Big-Vul dataset, and 66.29% on CWE-416 (Use After Free) in the DIVERSEVUL dataset. In contrast, SVuLD only achieves an F1-score of 37.59% and 53.58%, respectively. The main reason for the result is that constrained by the inherent limitations of linear Transformer-like architectures in learning structural semantics, SVuLD fails to capture data-dependence information which is tightly related to CWE-416 and CWE-476. Furthermore, we observe that having more training samples for a particular CWE does not necessarily result in the model learning it better than minor types of vulnerabilities, which is consistent with a recent empirical study [54]. For instance, SNOPY achieves more than 70% F1-score on CWE-787 and CWE-476, which only account for 2.25% and 2.45% of all vulnerable samples in the Big-Vul dataset. This result demonstrates the potential of SNOPY in detecting certain types of vulnerabilities with limited labeled data.

**Answer to RQ2:** On two large-scale vulnerability datasets with CWE information, SNOPY produces substantial improvements of up to 21.80% and 20.78% in terms of F1-score on average over the previous best-performing baseline in detecting different types of real-world vulnerabilities.

### 5.3 RQ3: Ablation Study

**Experiment Setup.** For sample denoising, we construct the following two variants of SNOPY for comparison: (1) without VCCs (denoted as *w/o VCCs*): performing noise cleansing only based on the disclosed vulnerable functions and corresponding patched versions in VFCs; and (2) without sample denoising (denoted as *w/o SD*): directly feeding the entire vulnerable and benign functions into the DL model for training. For causal graph learning, we compare our proposed CA-GAT with the following four variants: (3) without node attention (denoted as *w/o NA*): eliminating the node attention mask; (4) without edge attention (denoted as *w/o EA*): excluding the edge attention mask; (5) without feature caching scheme (denoted as *w/o FCS*): constraining the types of spurious features to each mini-batch; and (6) without causal intervention (*w/o CI*): directly leveraging the graph-level embedding of the input sample for prediction like REVEAL [8]. In each ablation study, we remove one component at a time to examine the individual contributions of key designs.

**Results.** Figure 7 presents the results of SNOPY and its six variants. We can observe that **all key designs are essential to achieve the best performance**. Particularly, without the sample denoising, the F1-score on the three datasets drops by 7.18%, 20.07%, and 15.59%, respectively. It demonstrates the necessity of filtering vulnerability-irrelevant parts of vulnerable samples for DL models. For causal graph learning, SNOPY with the node attention, edge attention, and FCS bring 5.45%-12.77%, 2.86%-5.82%, and 5.19%-20.74% improvements in F1-score on the three datasets, respectively. Among all variants, we find that **the causal intervention module makes the greatest contribution**. Compared to the variant without causal intervention, SNOPY improves the F1-score by 12.26%, 43.91%, and

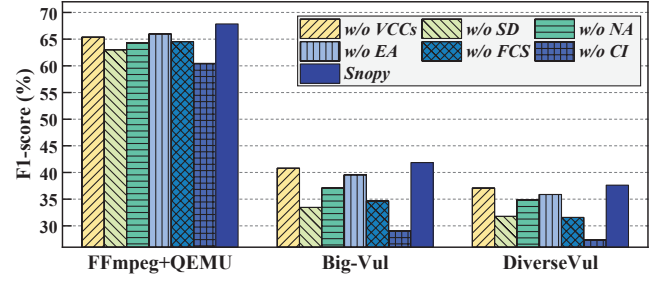


Figure 7: The performance of different variants of SNOPY on the three datasets.

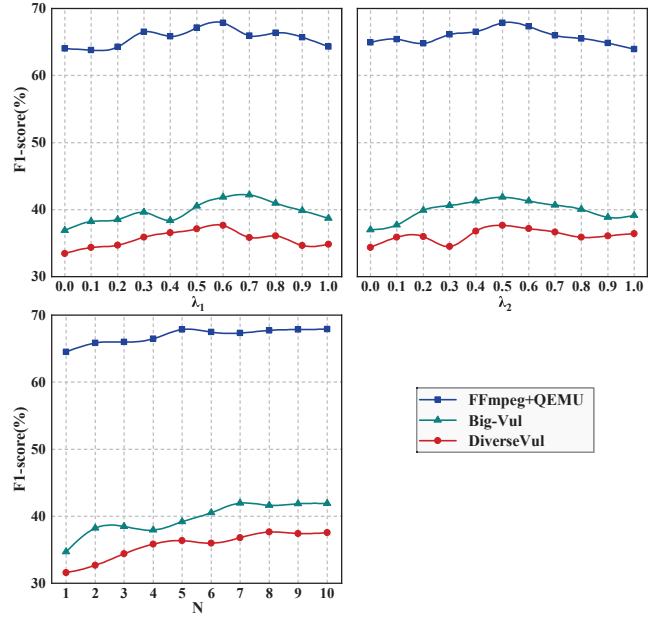


Figure 8: Parameter analysis of loss coefficients and the capacity of FCS.

37.32% on the FFmpeg+QEMU, Big-Vul, and DIVERSEVUL datasets, respectively. The results indicate that our proposed causal intervention module facilitates the causal feature learning and brings a performance improvement in vulnerability detection.

**Answer to RQ3:** Both sample denoising and causal graph learning are essential for the performance of SNOPY. The most important component of SNOPY is the causal intervention module that results in at most 30.51% improvement in F1-score.

## 6 DISCUSSION

### 6.1 Sensitivity Analysis

**Motivation.** In our approach, two sets of key hyper-parameters, loss coefficients  $\lambda_1$  &  $\lambda_2$  and capacity  $N$  of FCS, affect the performance of SNOPY. The former controls the intensity of feature disentanglement and causal intervention, the latter enriches the diversity

```

Vulnerability-Fixing Commit (e4571b8c) of CVE-2021-3739
1 int btrfs_rm_device(struct btrfs_fs_info *fs_info,
2                     const char *device_path, u64 devid)
3 {
4     struct btrfs_device *device; ← Rank 4
5     device = btrfs_find_device_by_devspec(fs_info, devid,
6     device_path); ← Rank 2
7     if (IS_ERR(device)) {
8         if (PTR_ERR(device) == -ENOENT &&
9             strcmp(device_path, "missing") == 0) ← Rank 1
10            device_path && strcmp(device_path, "missing") == 0)
11                ret = BTRFS_ERROR_DEV_MISSING_NOT_FOUND;
12            else
13                ret = PTR_ERR(device);
14            goto out;
15 }

```

**Figure 9: A NULL pointer dereference (CWE-476) vulnerability correctly detected by SNOPEY. The yellow-shaded statements positively contribute to SNOPEY’s prediction.**

of spurious features for causal intervention. Therefore, we vary these hyper-parameters to assess SNOPEY’s sensitivity towards them. **Experiment Setup.** To keep simplicity, all other configurations are kept consistent with RQ1, including data partition and metric computation. For loss coefficients, we fix one as 0.5, and test the other one at scale  $[0, 1]$ , incrementing in steps of 0.1. For the capacity  $N$  of FCS, the value is varied from 0 to 10 with an interval of 1.

**Results of Loss Coefficients.** The evaluation results on the three datasets are shown in the top part of Figure 8. We can observe that, different weights of feature disentanglement  $\lambda_1$  and causal intervention  $\lambda_2$  have varying impact on SNOPEY’s performance. In particular, the F1-score of SNOPEY stably goes up with the increasing of  $\lambda_1$  and  $\lambda_2$ , and reaches the optimal performance around 0.6 and 0.5, respectively. After that, both two coefficients lead to varying degrees of performance degradation.

**Results of Varying Capacity.** Figure 8 (bottom) presents the performance of SNOPEY with varying capacity  $N$ . From the results, it is evident that increasing the number of candidate spurious features improves the overall performance up to a certain point, underscoring the significance of diverse spurious features in enhancing model performance. Interestingly, we find that the performance plateaus when  $N$  exceeds 6. This denotes that our SNOPEY can deliver satisfactory performance with limited memory overhead.

**Summary:** Different weights of loss coefficients have varying impact on SNOPEY’s performance, and the larger capacity of FCS may not always guarantee better performance. Our default hyper-parameter settings achieve optimal results.

## 6.2 Case Study: Interpretability

**Motivation.** While demonstrated superior performance, the black-box nature hinders the adoption of current neural vulnerability detectors in practice because they fail to explain why a given code is predicted as vulnerable [30]. For this purpose, we conduct a case study to further investigate whether our proposed SNOPEY effectively makes predictions based on real vulnerability patterns.

**Experiment Setup.** In line with previous research [7, 36], we formalize vulnerability interpretation as a localization task, i.e., pointing out a set of crucial statements  $\{s_i, \dots, s_j\} \in P$  that are

most relevant to the detected vulnerable code  $P$ . To do so, we calculate the attention score  $\alpha_{c_i}$  of each node  $v \in \mathcal{V}$  in the causal sub-graph  $\mathcal{G}_c$ , as defined in Equation (6). Finally, Top-5 important statements are derived as interpretations.

**Results.** Figure 9 presents a correctly detected vulnerability (CVE-2021-3739<sup>7</sup>) in the DIVERSEVUL dataset. The vulnerable function has been simplified for a clear illustration. Since `btrfs_rm_device()` itself can have case where it only receives `devid` (at line 1), a NULL pointer dereference vulnerability can be easily triggered when calling a non-existing `device_path` via `strcmp()` (at line 8). Overall, the vulnerability-triggering statement obtains the highest attention score (i.e., Rank 1) and its contexts (line 3 and line 5), which reflect the root cause of this vulnerability, are also included in SNOPEY’s Top-5 explanations. This proves the practicality of SNOPEY when applied to real-world usage because SNOPEY can not only accurately detect vulnerabilities, but also narrow down the scope of manual review by providing a small fragment of suspicious code elements.

## 6.3 Threats to Validity

**Threats to Internal Validity** come from the quality of our experimental datasets. We evaluated the detection performance of SNOPEY on the three large-scale benchmark datasets, including FFmpeg+QEMU, Big-Vul and DIVERSEVUL. However, existing vulnerability datasets have been reported to exhibit varying degrees of quality issues such as noisy labels and duplication [15]. To reduce the likelihood of experiment biases, we adhere to the best practice [19], which discards duplicated samples by comparing the MD5 hashes of the pre- and post-commit versions of the changed functions, and labels vulnerable samples based on two customized rules. **Threats to External Validity** refer to the generalizability of our approach. We only evaluate our approach on C/C++ datasets, and thus our experimental results may not generalizable to other programming languages (e.g., Java and Python). However, we believe the key unique design of SNOPEY (i.e., leveraging vulnerability-related code changes to reduce vulnerability-irrelevant part of vulnerable samples, and constructing CA-GAT to learn causal vulnerability features) is language-agnostic, and thus our approach can be easily ported for a new programming language. Another threat is the imprecise identification of VCCs, which may impair the accuracy of essential vulnerable line localization. To mitigate this, we employ the state-of-the-art V-SZZ algorithm to identify the induced versions from disclosed vulnerable functions.

## 7 RELATED WORK

### 7.1 Learning-based Vulnerability Detection

According to their employed model architectures, current DL-based vulnerability detectors typically can be categorized into two groups: DNN- and LLM-based approaches.

**7.1.1 DNN-based Approaches.** Early studies [17, 38, 39] primarily relied on sequential neural networks, such as Long Short-Term Memory (LSTM) [28] and Gated Recurrent Unit (GRU) [12], to learn vulnerability features from flatten AST or token sequence. However, these approaches failed to capture well-defined semantics of the program structure. To address this issue, Devign [71] leveraged

<sup>7</sup><https://nvd.nist.gov/vuln/detail/CVE-2021-3739>

Gated Graph Neural Network (GGNN) [35] with a convolutional module to extract rich structural information of vulnerable code from joint code graphs. This progress promotes the recent popularity of GNN-based solutions [5, 8, 11, 36]. For instance, AMPLE [61] simplified the input program graph to alleviate the long-term dependency problems and fused local and global heterogeneous node relations for better representation learning.

**7.1.2 LLM-based Approaches.** As large code models have shown great potential in automating various software engineering tasks, LLMs-based vulnerability detection approaches have gained traction [18, 24, 27, 45, 67]. These works either directly train a vulnerability classifier based on fine-tuned large code models (e.g., CodeBERT [21] and UniXcoder [26]), or re-train their own LLMs from scratch to incorporate domain knowledge beneficial for downstream vulnerability analysis tasks. For example, LINEVUL [24] employed a BERT-like model to generate representations of source code for vulnerability detection, and leveraged the attention mechanism [68] to locate vulnerable statements. SVuLD [45] adopted contrastive learning [69, 70] to fine-tune the pre-trained UniXcoder to discriminate the semantic difference among lexical similar functions.

Unlike the above approaches that adapt advanced DL models to learn vulnerability features from the entire vulnerable functions, our work bridges sample denoising with causal graph learning to suppress the negative impact of noise information while promoting learning of real vulnerability patterns for effective detection.

## 7.2 Causal Theory in Software Engineering

Theory of Causation [29] endows the model with the ability to pursue real causality without the interference from confounding factors. Such mechanism is a useful verification tool to achieve a more complete understanding of black-box neural models in SE tasks, such as code completion [51] and vulnerability detection [7, 47, 50]. COCA [7] proposed a dual-view causal inference-based approach to derive crucial code statements that are most decisive to the detected vulnerability as interpretations. CausalVul [50] discovered that weakly-robust variable and API names can be abused as spurious features, and applied causal learning to disable the detection model from using them for prediction. Our work is differentiated by the fact that we focus on capturing causal features for more effective vulnerability detection, instead of improving the adversarial robustness and interpretability of code models. As such, our research has a completely different goal as compared to them.

## 8 CONCLUSION AND FUTURE WORK

In this paper, we propose SNOPY, a novel DL-based approach, which bridges sample denoising with causal graph learning for effective detection. SNOPY adopts a change-based sample denoising approach to weed out vulnerability-irrelevant parts of vulnerable functions, and constructs a novel Causality-Aware Graph Attention Network (CA-GAT) to capture real vulnerability patterns for prediction. Experiments on the three public benchmark datasets show that SNOPY outperforms the state-of-the-art baselines by an average of 27.22%, 85.89%, and 75.50% in terms of F1-score, respectively.

In the future, we plan to work with our industry partners to deploy SNOPY in their proprietary security systems to uncover

real-world vulnerabilities. In addition, we would like to develop an explanation module to provide not only fine-grained vulnerable lines, but also user-friendly explanatory information, such as the root causes, behaviors, and consequences of vulnerabilities.

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